

# **OICOX** Welding robot

Systematic automated welding and cutting

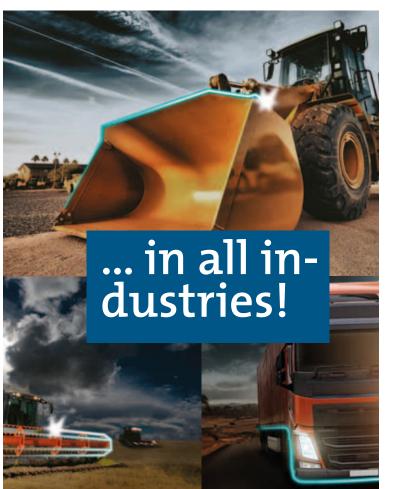


Weld your way.

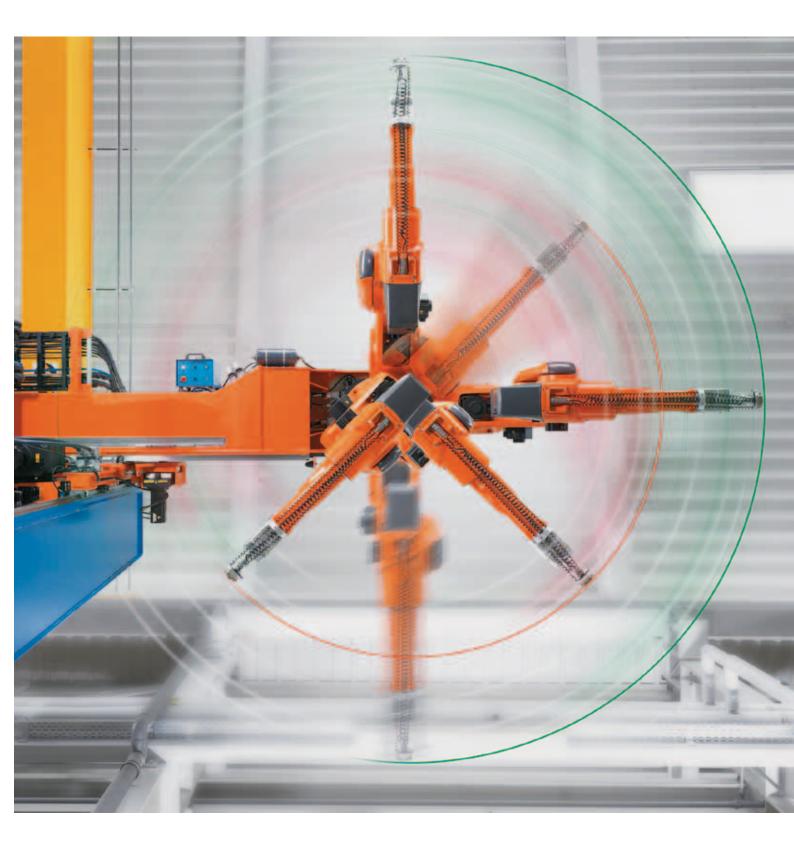
www.cloos.de

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# **QIROX Welding robot**

### Welding robots in the international top class

As one of the leading specialists in the development and manufacture of highvalue welding robots for demanding industrial applications, CLOOS uses its decades-old know-how for continuous development. Thanks to the integration of innovative technologies, the new generation of QIROX welding robots guarantees additional customer value and production advantages. Among the particular highlights are the complete reworking of the product design and the introduction of an optional seventh axis. Both innovations contribute to a considerable increase in the flexibility and dynamics of the QIROX welding robots. As a result, the automated welding processes can be configured in a significantly more efficient manner.

#### Advantages for increased productivity

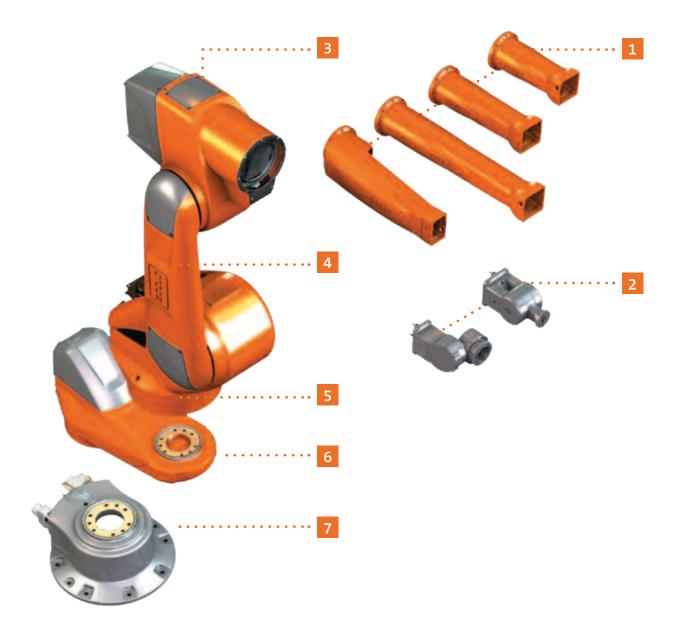
- Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- Highest flexibility in the equipment by modular design of the robot mechanics
- Optional seventh axis for increasing the working envelope and optimum positioning of the welding torch
- Less wear and improved, more user-friendly operation via optimised cables, plugs and motor protection
- Best processing quality due to a high repeatability
- High offset speeds reduce the cycle times
- The proven CLOOS quality ensures a particularly long service life and extended maintenance intervals
- Systems matched to production requirements, including suitable hardware and software



# Variants

# Many variants from one construction kit

The most dynamic feature of the QIROX robot is the modular design of all the mechanics. All components of the welding robot – from the robot base to the axis tube – are perfectly matched to each other. By using different components, a customised welding robot can be generated for every production requirement.



**QRH -280** Wrist with hollow shaft

Page 8



**QRC-290** Classic wrist

Page **10** 



QRC-320/350/410-H Classic wrist High robot base

Page **12** 

#### Arm tubes

Design depending on the working range



Classic Hollow shaft

- 3 Shoulder joint
- 4 Pivot arm
- 5 Angular base
- 6 7th axis

Enlarged working envelope

7

### Robot base

Standard for upright and overhead mounting High for upright mounting



QRC-320/350/410 Classic wrist

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QRH-360/390 Wrist with hollow shaft

Page **18** 



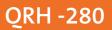
QRC-350/410-E Classic wrist with 7th axis

Page **20** 



QRH-360/390-E Wrist with hollow shaft, with 7th axis

Page 22



Compact robot mechanics Wrist with hollow shaft











# QIROX QRH Robot: The welding specialist

The QIROX QRH-280 is a six-axis articulated arm robot. It is mounted on a base or at a robot positioner, so that the robot is either used in upright or in overhead position. The cable assembly is led through a hollow shaft which is integrated in the wrist. The QIROX QRH-280 takes up welding torches weighing up to 6 kg at the hollow shaft wrist.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Process safety: The hollow shaft integrated in the wrist ensures an increased level of stability of the torch cable assembly.
- 3. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 4. Speed: High axis speeds for reduced cycle times
- 5. Quality: Repeatability, long service life and maintenance intervals

	Robot QRH-280-6
Swivelling range	
- Axis 1	+170°/-170°
- Axis 2	+90°/-125°
- Axis 3	-180° / +70°
- Axis 4	+179° / -179°
- Axis 5	+125°/-125°
- Axis 6	+300°/-300°
Swivelling speed	
- Axis 1	200 °/sec
- Axis 2	200 °/sec
- Axis 3	200 °/sec
- Axis 4	497 °/sec
- Axis 5	542 °/sec
- Axis 6	750 °/sec
Operating range	Ø 3800 mm
Operating range Axis 5 +90°	Ø 2800 mm
Operating range height	2250 mm
Payload	6.00 kg
Repeatability	$\Delta \leq s$ +/- 0,05 mm
Collision radius	500 mm
Floor space	Ø 400 mm
Weight	90 kg



Compact robot mechanics











# QIROX QRC-290 Robot: The entry model

The QIROX QRC-290 is a six-axis articulated arm robot. It is mounted on a base or at a robot positioner, so that the robot is either used in upright or in overhead position. The QIROX QRC-290 robot has a classic wrist where gas- and water cooled welding torches with a weight of up to 4 kg can be mounted.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 3. Speed: High axis speeds for reduced cycle times
- 4. Floor space: Very low space needed at a large range
- 5. Quality: Repeatability, long service life and maintenance intervals

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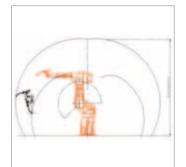
	Robot QRH-290-4
Swivelling range	
- Axis 1	+120°/-120°
- Axis 2	+160°/-90°
- Axis 3	+80° / -200°
- Axis 4	+190°/-190°
- Axis 5	+140° / -140°
- Axis 6	+360°/-360°
Swivelling speed	
- Axis 1	230 °/sec
- Axis 2	230 °/sec
- Axis 3	230 °/sec
- Axis 4	430 °/sec
- Axis 5	430 °/sec
- Axis 6	630 °/sec
Operating range	Ø 3740 mm
Operating range Axis 5 +90°	Ø 2920 mm
Operating range height	1940 mm
Pay load	4.00 kg
Repeatability	$\Delta \leq s + - 0.15 \text{ mm}$
Collision radius	Ø 550 mm
Floor space	285 mm x 285 mm
Weight	105 kg

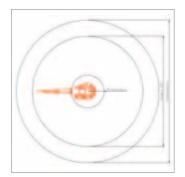
# QRC-320/350/410-H

Robot mechanics Classic wrist, high robot base











### QIROX QRC Robot: The all-rounder

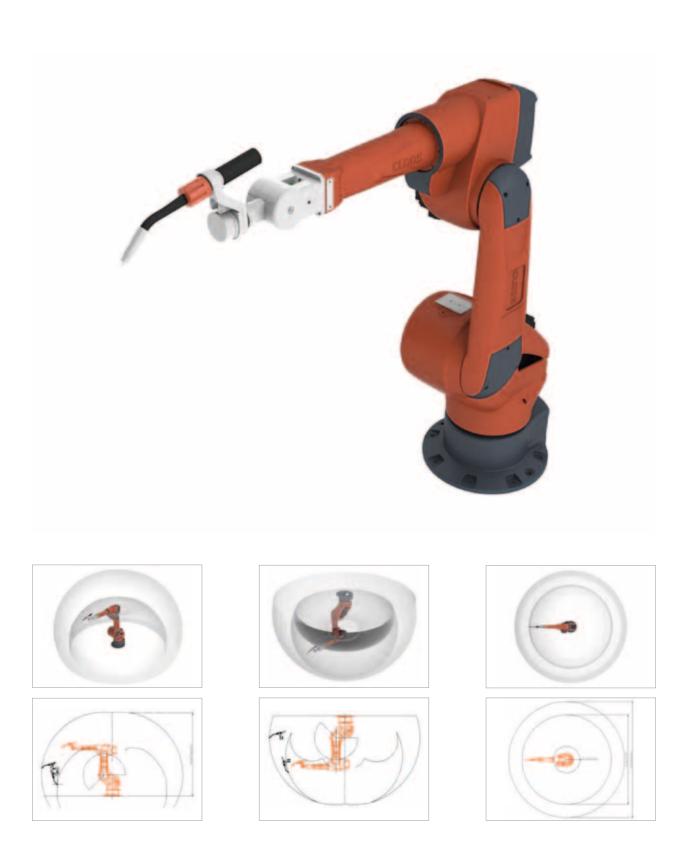
The QIROX QRC-320/350/410-H is a six-axis articulated arm robot. The robot has a high base which was particularly developed for floor mounting and is mounted in upright position on the shop floor, a base frame or at a robot positioner. The QIROX QRC-320/350/410-H robot has a classic wrist where welding torches, flame cutters and other working tools with a weight of up to 15/10 kg can be mounted. The integration of a changing tool on the wrist allows to use more processes with a robot.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 3. Speed: High axis speeds for reduced cycle times
- 4. Application range: Changing tool allows to use different processes with a robot
- 5. Quality: Repeatability, long service life and maintenance intervals

Robot high base	QRC-320-H-15	QRC-350-H-15	QRC-410-H-10
Swivelling range			
- Axis 1	+170/-170°	+170/-170°	+170 / -170°
- Axis 2	+135/-90°	+135/-90°	+135 / -90°
- Axis 3	+80/-210°	+80/-210°	+80/-210°
- Axis 4	+179/-179°	+179/-179°	+179 / -179°
- Axis 5	+135/-135°	+135/-135°	+135 / -135°
- Axis 6	+300/-300°	+300/-300°	+300 / -300°
Swivelling speed			
- Axis 1	184 °/sec	184 °/sec	184 °/sec
- Axis 2	184 °/sec	184 °/sec	184 °/sec
- Axis 3	177 °/sec	177 °/sec	177 °/sec
- Axis 4	497 °/sec	497 °/sec	497 °/sec
- Axis 5	542 °/sec	542 °/sec	542 °/sec
- Axis 6	528 °/sec	528 °/sec	528 °/sec
Operating range	Ø 4200 mm	Ø 4430 mm	Ø 5000 mm
Operating range Axis 5 +90°	Ø 3200 mm	Ø 3440 mm	Ø 4020 mm
Operating range height	2790 mm	2900 mm	3200 mm
Pay load	15.00 kg	15.00 kg	10.00 kg
Repeatability	$\Delta \leq$ s +/- 0,1 mm	$\Delta \leq$ s +/- 0,1 mm	$\Delta \leq$ s +/- 0,1 mm
Collision radius	500 mm	500 mm	500 mm
Floor space	Ø 500 mm	Ø 500 mm	Ø 500 mm
Weight	255 kg	255 kg	260 kg

# QRC-320/350/410

Robot mechanics Classic wrist



### QIROX QRC Robot: The all-rounder

The QIROX QRC-320/350/410 is a six-axis articulated arm robot. The robot is mostly used in upright or overhead position and is mounted on a base or directly at a robot positioner. The QIROX QRC-320/350/410 robot has a classic wrist where welding torches, flame cutters and other working tools with a weight of up to 15/10 kg can be mounted. The integration of a changing tool on the wrist allows to use more processes with a robot.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 3. Speed: High axis speeds for reduced cycle times
- 4. Application range: Changing tool allows to use different processes with a robot
- 5. Quality: Repeatability, long service life and maintenance intervals

	QRC-320-15	QRC-350-15	QRC-410-10
Swivelling range			
- Axis 1	+170/-170°	+170/-170°	+170 / -170°
- Axis 2	+135/-90°	+135/-90°	+135 / -90°
- Axis 3	+80/-210°	+80/-210°	+80/-210°
- Axis 4	+179/-179°	+179/-179°	+179 / -179°
- Axis 5	+135/-135°	+135/-135°	+135 / -135°
- Axis 6	+300/-300°	+300/-300°	+300 / -300°
Swivelling speed			
- Axis 1	184 °/sec	184 °/sec	184 °/sec
- Axis 2	184 °/sec	184 °/sec	184 °/sec
- Axis 3	177 °/sec	177 °/sec	177 °/sec
- Axis 4	497 °/sec	497 °/sec	497 °/sec
- Axis 5	542 °/sec	542 °/sec	542 °/sec
- Axis 6	528 °/sec	528 °/sec	528 °/sec
Operating range	Ø 4200 mm	Ø 4430 mm	Ø 5000 mm
Operating range Axis 5 +90°	Ø 3200 mm	Ø 3440 mm	Ø 4020 mm
Operating range height	2470 mm	2580 mm	2880 mm
Pay load	15.00 kg	15.00 kg	10.00 kg
Repeatability	$\Delta \leq$ s +/- 0,1 mm	$\Delta \leq$ s +/- 0,1 mm	$\Delta \leq s +/- 0,1 \text{ mm}$
Collision radius	500 mm	500 mm	500 mm
Floor space	Ø 500 mm	Ø 500 mm	Ø 500 mm
Weight	235 kg	235 kg	240 kg

# QRH-360/390-H

Robot mechanics Hollow shaft wrist, high robot base



# QIROX QRH Robot: The welding specialist

The QIROX QRH-360/390-H is a six-axis articulated arm robot. The robot has a high base which was particularly developed for floor mounting and is mounted in upright position on the shop floor, a base frame or at a robot positioner. The cable assembly is led through a hollow shaft which is integrated in the wrist. The QIROX QRH-360/390-H takes up welding torches weighing up to 15/10 kg at the hollow shaft wrist.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Process safety: The hollow shaft integrated in the wrist ensures an increased level of stability of the torch cable assembly.
- 3. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 4. Speed: High axis speeds for reduced cycle times
- 5. Quality: Repeatability, long service life and maintenance intervals

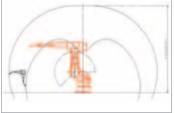
Robot high base	QRH-360-H-15	ORH-390-H-10
Swivelling range	2	
- Axis 1	+170/-170°	+170 / -170°
- Axis 2	+135/-90°	+135/-90°
- Axis 3	+80/-210°	+80/-210°
- Axis 4	+179/-179°	+179 / -179°
- Axis 5	+125/-125°	+125 / -125°
- Axis 6	+270/-270°	+270 / -270°
Swivelling speed		
- Axis 1	184 °/sec	184 °/sec
- Axis 2	184 °/sec	184 °/sec
- Axis 3	177 °/sec	177 °/sec
- Axis 4	497 °/sec	497 °/sec
- Axis 5	542 °/sec	542 °/sec
- Axis 6	528 °/sec	528 °/sec
Operating range	Ø 4570 mm	Ø 4900 mm
Operating range Axis 5 +90°	Ø 3570 mm	Ø 3900 mm
Operating range height	3000 mm	3180 mm
Pay load	15.00 kg	10.00 kg
Repeatability	$\Delta \leq$ s +/- 0,1 mm	$\Delta \leq$ s +/- 0,1 mm
Collision radius	500 mm	500 mm
Floor space	Ø 500 mm	Ø 500 mm
Weight	255 kg	260 kg



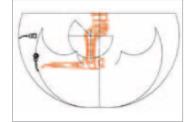
Robot mechanics Hollow wrist

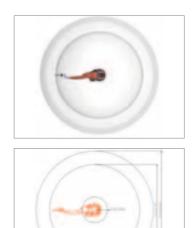












# QIROX QRH Robot: The welding specialist

The QIROX QRH-360/390 is a six-axis articulated arm robot. The robot is mostly used in upright or overhead position and is mounted on a base or at a robot positioner. The cable assembly is led through a hollow shaft which is integrated in the wrist. The QIROX QRH-360/390 takes up welding torches weighing up to 15/10 kg at the hollow shaft wrist.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Process safety: The hollow shaft integrated in the wrist ensures an increased level of stability of the torch cable assembly.
- 3. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 4. Speed: High axis speeds for reduced cycle times
- 5. Quality: Repeatability, long service life and maintenance intervals

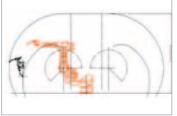
Swielling range- Axis 1+170/-170°+170/-170°- Axis 2+135/-90°+135/-90°- Axis 3+80/-210°+80/-210°- Axis 4+179/-179°+179/-179°- Axis 5+125/-125°+270/-270°- Axis 6>270/-270°+270/-270°- Axis 1184°sc184°sc- Axis 2184°sc184°sc- Axis 3184°sc184°sc- Axis 4470°sc520°sc- Axis 5524°sc521°sc- Axis 6528°sc528°sc- Axis 6528°sc528°sc- Axis 6528°sc528°sc- Axis 6528°sc528°sc- Qierating range Axis 5+90°63570 mm6400 mm- Repatability501m501m- Repatability501m501m- Rorspace600 mm500 mm- Rorspace500 mm500 mm <th></th> <th>QRH-360-15</th> <th>QRH-390-10</th>		QRH-360-15	QRH-390-10					
Axis 2+135 / -90°+135 / -90°- Axis 3+80 / -210°+80 / -210°- Axis 4+179 / -179°+179 / -179°- Axis 5+125 / -125°+125 / -125°- Axis 6+270 / -270°+270 / -270°- Axis 1184 °/sec184 °/sec- Axis 2184 °/sec184 °/sec- Axis 3177 °/sec177 °/sec- Axis 4497 °/sec497 °/sec- Axis 5542 °/sec542 °/sec- Axis 6542 °/sec542 °/sec- Axis 6542 °/sec542 °/sec- Axis 6542 °/sec542 °/sec- Axis 6542 °/sec542 °/sec- Derating range Axis 5 +90°Ø 370 mmØ 3900 mmOperating range height500 kg100 kgPay load500 kg500 kgFor spaceØ 500 mm500 kg	Swivelling range							
Axis 3+80 / -210°+80 / -210°- Axis 4+179 / -179°+179 / -179°- Axis 5+125 / -125°+125 / -125°- Axis 6+270 / -270°+270 / -270°- Axis 6-270 / -270°-270°- Axis 1184 °/sec184 °/sec- Axis 2184 °/sec184 °/sec- Axis 3177 °/sec177 °/sec- Axis 4497 °/sec497 °/sec- Axis 5528 °/sec528 °/sec- Axis 6282 °/sec528 °/secOperating range Axis 5 +90°64570 mm64900 mmOperating range height680 mm3800 mmPay load15.00 kg10.00 kgRepeatabilityA < s +/-0.1 mm	- Axis 1	+170/-170°	+170/-170°					
- Axis A       +179/-179°       +179/-179°         - Axis S       +125/-125°       +125/-125°         - Axis 6       +270/-270°       +270/-270°         - Axis 6       +270/-270°       +270/-270°         - Axis 1       184 °sec       184 °sec         - Axis 2       184 °sec       184 °sec         - Axis 3       177 °sec       177 °sec         - Axis 4       497 °sec       497 °sec         - Axis 5       528 °sec       528 °sec         - Axis 6       528 °sec       528 °sec         Operating range Axis 5 +90°       63570 mm       6400 mm         Operating range Axis 5 +90°       6360 mm       3600 mm         Pay load       15.0 kg       10.0 kg         Repeatability       As s +/ 0.1 mm       As s +/ 0.1 mm         For space       900 mm       500 mm	- Axis 2	+135/-90°	+135 / -90°					
Axis 5+125 / 125°+125 / 125°- Axis 6+270 / 270°+270 / 270°Swivelling speed- Axis 1184 °/sec184 °/sec- Axis 2184 °/sec184 °/sec- Axis 3177 °/sec177 °/sec- Axis 4497 °/sec497 °/sec- Axis 5528 °/sec528 °/sec- Axis 6528 °/sec528 °/sec- Derating range Axis 5 +90°64570 mm64900 mmOperating range height2680 mm3600 mmPay load15.00 kg10.00 kgRepeatability62 s +/- 0.1 mm610 sin maintainsCollision radius600 mm500 mmFor space600 mm500 mm	- Axis 3	+80/-210°	+80/-210°					
Axis 6+270 / 270°+270 / 270°Swielling speed- Axis 1184 °/sc184 °/sc- Axis 2184 °/sc184 °/sc- Axis 3177 °/sc177 °/sc- Axis 4497 °/sc497 °/sc- Axis 5542 °/sc528 °/sc- Axis 6288 °/sc288 °/scOperating range Axis 5 +90°6450 mm6400 mmOperating range height150 Ng100 NgPapeabilitySa s +/-0,1 mmSa s +/-0,1 mmOperating range Mathematica500 mm500 mmPapeabilitySa s +/-0,1 mmSa s +/-0,1 mmPapeabilitySa s mathematicaSa s mathematicaPapeabilitySa s +/-0,1 mmSa s +/-0,1 mmPapeabilitySa s mathematicaSa s mathematicaPapeabilitySa s mathematicaSa s mathematicaPapeabilitySa s +/-0,1 mmSa s +/-0,1 mmPapeabilitySa s +/-0,1 mmSa s +/-0,1 mm </td <td>- Axis 4</td> <td>+179/-179°</td> <td>+179/-179°</td>	- Axis 4	+179/-179°	+179/-179°					
Swivelling speed- Axis 1184 °sec184 °sec- Axis 2184 °sec184 °sec- Axis 3177 °sec177 °sec- Axis 4497 °sec497 °sec- Axis 5542 °sec542 °sec- Axis 628 °sec58 °secOperating range Axis 5 +90°04570 mm380 mmOperating range height260 mm260 mmPayload5.0 kg3.0 kgRepeatability6.5 k °c 0.1 mmCollision radius500 mm500 mmFoor space9.00 mm500 mm	- Axis 5	+125/-125°	+125 / -125°					
- Axis 1       184 °sec       184 °sec         - Axis 2       184 °sec       184 °sec         - Axis 3       177 °sec       177 °sec         - Axis 4       97 °sec       97 °sec         - Axis 5       542 °sec       528 °sec         - Axis 6       283 °sec       528 °sec         Operating range       04570 mm       04900 mm         Operating range Axis 5 +90°       03570 mm       03900 mm         Operating range Axis 5 +90°       2680 mm       1860 mm         Pay load       15.00 kg       10.00 kg         Repeatability       63570 mm       0.400 kg         Collision radius       500 mm       580 radius         For space       900 mm       10.00 kg	- Axis 6	+270/-270°	+270 / -270°					
Axis 2184 °/sec184 °/sec- Axis 3177 °/sec177 °/sec- Axis 4497 °/sec497 °/sec- Axis 5542 °/sec542 °/sec- Axis 6528 °/sec528 °/secOperating range Axis 5 +90°04570 mm04900 mmOperating range Axis 5 +90°2680 mm3600 mmOperating range Axis 5 +90°500 mm500 mm<	Swivelling speed							
- Axis 3       177 °/sec       177 °/sec         - Axis 4       497 °/sec       497 °/sec         - Axis 5       542 °/sec       542 °/sec         - Axis 6       528 °/sec       528 °/sec         Operating range Axis 5 +90°       Ø 4570 mm       Ø 4900 mm         Operating range Axis 5 +90°       Ø 3570 mm       Ø 3900 mm         Operating range Axis 5 +90°       Ø 680 mm       Ø 600 mm         Operating range Axis 5 +90°       Ø 680 mm       Ø 600 mm         Operating range Axis 5 +90°       Ø 680 mm       Ø 600 mm         Operating range Axis 5 +90°       Ø 600 mm       Ø 600 mm         Operating range Axis 5 +90°       Ø 600 mm       Ø 900 mm         Operating range Axis 5 +90°       Ø 600 mm       Ø 900 mm         Operating range Axis 5 +90°       Ø 600 mm       Ø 900 mm         Operating range Axis 5 +90°       Ø 600 mm       Ø 900 mm         Operating range Axis 5 +90°       Ø 500 mm       Ø 600 mm         Operating range Axis 5 +90°       Ø 500 mm       Ø 500 mm	- Axis 1	184 °/sec	184 °/sec					
- Axis 4       497 °/sec       497 °/sec         - Axis 5       542 °/sec       542 °/sec         - Axis 6       528 °/sec       528 °/sec         Operating range       04570 mm       04900 mm         Operating range Axis 5 +90°       03570 mm       0300 mm         Operating range height       1500 kg       1000 kg         Pay load       528 °/sec       10.0 kg         Repeatability       630 mm       63 sec         Collision radius       500 mm       500 mm	- Axis 2	184 °/sec	184 °/sec					
- Axis 5542 °/sec542 °/sec- Axis 6528 °/sec528 °/secOperating rangeØ4570 mmØ4900 mmOperating range Axis 5 +90°Ø3570 mmØ3900 mmOperating range height2680 mm860 mmPay load15.00 kg10.00 kgRepeatabilityS00 mmS00 mmCollision radius500 mm500 mmFloor spaceØ500 mmS00 mm	- Axis 3	177 °/sec	177 °/sec					
- Axis 6528 °/sec528 °/secOperating rangeØ 4570 mmØ 4900 mmOperating range Axis 5 +90°Ø 3570 mmØ 3900 mmOperating range height2680 mm2860 mmPay load15.00 kg10.00 kgRepeatabilityA ≤ s +/- 0,1 mmA ≤ s +/- 0,1 mmCollision radius500 mm500 mmFloor spaceØ 500 mmØ 500 mm	- Axis 4	497 °/sec	497 °/sec					
Operating rangeØ 4570 mmØ 4900 mmOperating range Axis 5 +90°Ø 3570 mmØ 3900 mmOperating range height2680 mm2860 mmPay load15.00 kg10.00 kgRepeatabilityA ≤ s +/- 0,1 mmA ≤ s +/- 0,1 mmCollision radius500 mm500 mmFloor spaceØ 500 mmØ 500 mm	- Axis 5	542 °/sec	542 °/sec					
Operating range Axis 5 +90°Ø 3570 mmØ 3900 mmOperating range height2680 mm2860 mmPay load15.00 kg10.00 kgRepeatability $\Delta \leq s +/- 0,1$ mm $\Delta \leq s +/- 0,1$ mmCollision radius500 mm500 mmFloor space $\emptyset$ 500 mm $\emptyset$ 500 mm	- Axis 6	528 °/sec	528 °/sec					
Operating range height $2680 \text{ mm}$ $2860 \text{ mm}$ Pay load $15.00 \text{ kg}$ $10.00 \text{ kg}$ Repeatability $\Delta \le s + - 0.1 \text{ mm}$ $\Delta \le s + - 0.1 \text{ mm}$ Collision radius $500 \text{ mm}$ $500 \text{ mm}$ Floor space $\phi$ 500 mm $\phi$ 500 mm	Operating range	Ø 4570 mm	Ø 4900 mm					
Pay load         15.00 kg         10.00 kg           Repeatability         Δ ≤ s +/- 0,1 mm         Δ ≤ s +/- 0,1 mm           Collision radius         500 mm         500 mm           Floor space         Ø 500 mm         Ø 500 mm	Operating range Axis 5 +90°	Ø 3570 mm	Ø 3900 mm					
Repeatability $\Delta \le s +/- 0,1  \text{mm}$ $\Delta \le s +/- 0,1  \text{mm}$ Collision radius500 mm500 mmFloor space $\emptyset$ 500 mm $\emptyset$ 500 mm	Operating range height	2680 mm	2860 mm					
Collision radius500 mm500 mmFloor spaceØ 500 mmØ 500 mm	Payload	15.00 kg	10.00 kg					
Floor space Ø 500 mm Ø 500 mm	Repeatability	$\Delta \leq$ s +/- 0,1 mm	$\Delta \leq$ s +/- 0,1 mm					
	Collision radius	500 mm	500 mm					
Weight         235 kg         240 kg	Floor space	Ø 500 mm	Ø 500 mm					
	Weight	235 kg	240 kg					

# QRC-350/410-E

Robot mechanics Classic wrist 7th axis with enlarged working range

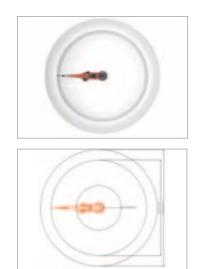












# QIROX QRC-410-10-E Robot: The all-rounder with a high range

The QIROX QRC-350/410-E is a six-axis articulated arm robot with an eccentric axis 7 which is integrated between robot base and centre point of axis 1. The movements of all seven robot axes are synchronised by 100 %. The robot is mostly used in upright or overhead position and is mounted on a base or directly at a robot positioner. The QIROX QRC-350/410-E robot has a classic wrist where welding torches, flame cutters and other working tools with a weight of up to 15/10 kg can be mounted. The integration of a changing tool on the wrist allows to use more processes with a robot.

- **1.** Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 3. Speed: High axis speeds for reduced cycle times
- 4. Application range: Changing tool allows to use different processes with a robot
- 5. Range: Seventh axis for increasing the working envelope and optimum positioning of the welding torch
- 6. Quality: Repeatability, long service life and maintenance intervals

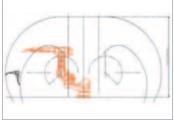
Robot 7th Axis	QRC-350-E-15	QRC-410-E-10
Swivelling range		
- Axis 1	+170/-170°	+170/-170°
- Axis 2	+135/-90°	+135 / -90°
- Axis 3	+80/-210°	+80/-210°
- Axis 4	+179/-179°	+179 / -179°
- Axis 5	+135/-135°	+135 / -135°
- Axis 6	+300/-300°	+300 / -300°
- Axis 7	+120/-120°	+120 / -120°
Swivelling speed		
- Axis 1	184 °/sec	184 °/sec
- Axis 2	184 °/sec	184 °/sec
- Axis 3	177 °/sec	177 °/sec
- Axis 4	497 °/sec	497 °/sec
- Axis 5	542 °/sec	542 °/sec
- Axis 6	528 °/sec	528 °/sec
- Axis 7	90 °/sec	90 °/sec
Operating range	Ø 5470 mm	Ø 6100 mm
Operating range Axis 5 +90°	Ø 4470 mm	Ø 5050 mm
Operating range height	2830 mm	3120 mm
Pay load	15.00 kg	10.00 kg
Repeatability	$\Delta \leq$ s +/- 0.1 mm	$\Delta \leq s +/- 0.1 \text{ mm}$
Collision radius	1050 mm	1050 mm
Floor space	Ø 500 mm	Ø 500 mm
Weight	345 kg	350 kg

# QRH-360/390-E

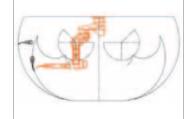
Robot mechanics Hollow shaft wrist 7th axis with enlarged working range

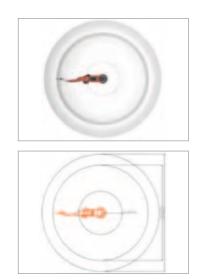












# QIROX QRC-E Robot: The welding specialist with a high range

The QIROX QRC-360/390-E is a six-axis articulated arm robot with an eccentric axis 7 which is integrated between robot base and centre point of axis 1. The movements of all seven robot axes are synchronised by 100 %. The robot is mostly used in upright or overhead position and is mounted on a base or at a robot positioner. The cable assembly is led through a hollow shaft which is integrated in the wrist. The QIROX QRH-360/390-E takes up welding torches weighing up to 15/10 kg at the hollow shaft wrist.

- 1. Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- 2. Process safety: The hollow shaft integrated in the wrist ensures an increased level of stability of the torch cable assembly.
- 3. Dynamics: Higher dynamics and weight reduction due to a leaner product design with rounded ergonomic forms
- 4. Speed: High axis speeds for reduced cycle times
- 5. Range: Seventh axis for increasing the working envelope and optimum positioning of the welding torch
- 6. Quality: Repeatability, long service life and maintenance intervals

Robot 7th Axis	QRH-360-E-15	QRH-390-E-10
Swivelling range		
- Axis 1	+170/-170°	+170 / -170°
- Axis 2	+135/-90°	+135 / -90°
- Axis 3	+80/-210°	+80/-210°
- Axis 4	+179/-179°	+179 / -179°
- Axis 5	+125/-125°	+125 / -125°
- Axis 6	+270/-270°	+270 / -270°
- Axis 7	+120/-120°	+120/-120°
Swivelling speed		
- Axis 1	184 °/sec	184 °/sec
- Axis 2	184 °/sec	184 °/sec
- Axis 3	177 °/sec	177 °/sec
- Axis 4	497 °/sec	497 °/sec
- Axis 5	542 °/sec	542 °/sec
- Axis 6	528 °/sec	528 °/sec
- Axis 7	90 °/sec	90 °/sec
Operating range	Ø 5680 mm	Ø 6030 mm
Operating range Axis 5 +90°	Ø 4620 mm	Ø 4960 mm
Operating range height	2930 mm	3110 mm
Pay load	15.00 kg	10.00 kg
Repeatability	$\Delta \leq$ s +/- 0.1 mm	$\Delta \leq s + - 0.1 \text{ mm}$
Collision radius	1050 mm	1050 mm
Floor space	Ø 500 mm	Ø 500 mm
Weight	345 kg	350 kg

# Attached parts Robot mechanics

# 1. Robot welding torches

Single wire torches Tandem welding torches

TIG welding torches

CLOOS robot welding torches are the result of years of development and experience in the field of automated MIG/MAG welding. The welding torch is mounted to the robot flange with a holder. An anti-collision sensor is integrated in the robot flange.

# 2. Tool changing system

Allows the combination of different processes or the use of several welding torches with different geometries at one robot.

# 3. Integrated DuoDrive wire drive unit

The intelligent DuoDrive wire drive system transports mainly thin and soft welding wires easily and reliably without restricting the robot's freedom of movement. The slim and compact design of the wire drive unit guarantees an optimum accessibility in confined spaces.

# 4. Other applications

We supply individual manufactures on demand:

Laser and laser hybrid

- Cutting
- Handling
- Special applications, e.g. Torch/gripper combination







# Efficiency ...



**Control Weld** Reliable MIG/MAG welding process for thin and thick materials



**Speed Weld** Stable MIG/MAG pulsed arc for numerous applications

Vari Weld

ing conditions

Cold Weld



**Rapid Weld** High-capacity MIG/MAG spray arc for efficient welding

MIG/MAG pulsed arc for optimum welding results even under demand-



for optimum results when welding sensitive materials **Tandem Weld** 

Heat-reduced MIG/MAG AC pulsed arc



MIG/MAG arcs for double capacity







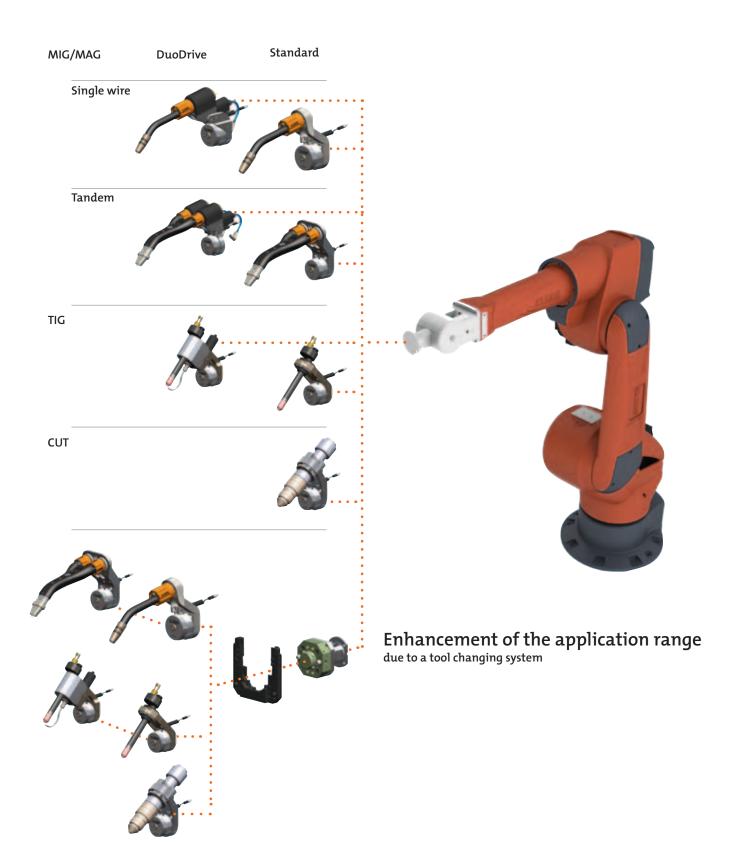
**Laser Hybrid Weld** Combination of laser welding and MIG/MAG arc for maximum efficiency and quality

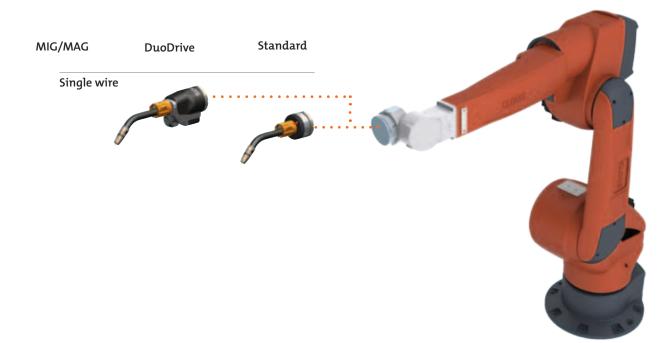
... due to modern processes



# Attached parts Robot mechanics

# The all-rounder QRC





# The welding specialist QRH

# Comparison of QIROX robots

Robot mechanics	Operating range [mm]	Pay load	MIG/MAG single wire	DuoDrive single wire	DuoDrive hollow shaft	MIG/MAG Tandem	DuoDrive Tandem	DIT	Laser Welding	Cut	Narrow gap blade	Changing tool	
QRH-280-6	Ø 3800 mm	6 kg	Х	X	Х								
QRC-290-4	Ø 3740 mm	4 kg	X					X					
QRC-320-15	Ø 4200 mm	15 kg	x	x		x	x	x	x	x	x	x	
QRC-350-15	Ø 4430 mm	15 kg	X	X		X	X	X	X	X	X	X	
QRC-410-10	Ø 5000 mm	10 kg	X	X		X	X	X		X		X	
		5											
QRC-350-E-15	Ø 5470 mm	15 kg	Х	Х		Х	Х	Х		Х	Х	Х	
QRC-410-E-10	Ø 6100 mm	10 kg	X	X		X	X	X		X		X	
QRH-360-15	Ø 4570 mm	15 kg	х	х	х								
~ QRH-390-10	Ø 4900 mm	10 kg	X	X	X								
2 333 10	¢ +500 mm	TO Kġ	^	^	^								
QRH-360-E-15	Ø 5680 mm	15 kg	X	X	X								
QRH-390-E-10	Ø 6030 mm	10 kg	Х	X	X								

# **Further information**

# Welding

#### Process diversity in perfection

With a large range of proven and innovative processes for manual and automated welding applications, we at CLOOS can offer solutions for the future providing excellent quality, maximum efficiency and productivity.





# **QIROX** Controller

#### Optimum "man-machine" interface

A digital drive system with high end distributed computing power ensures dynamic movement and a high path accuracy of the robot during welding. All processes are controlled by an industrial PC with the capacity to simultaneously control seven internal robot axes and up to twelve external peripheral axes.





# **QIROX** Sensors

#### Best quality at each weld seam

With our QIROX sensor systems you achieve optimum welding results and an excellent quality because of exact welding procedures. Four practice-proven CLOOS sensors are available for the most different materials and applications: Tactile sensor, arc sensor, laser offline sensor and laser online sensor.





# **Application examples**

**Customised technologies for the most different industries** With highly innovative products we work out individualised solutions to meet the growing requirements of your industry. For decades, customers from the most different industries have trusted in our welding technologies and our know-how.





# The way ...



#### Consulting

With this comprehensive "pre-service", we take care of your project from the beginning and transfer our integrated process expertise to your component.



#### Planning

We elaborate a solution which perfectly meets your individual requirements.



#### Design

Due to the modular design of our product series we develop customised solutions which meet all your production requirements.



#### Production

Welding machine and robot technology is our strength - including our core competence: the arc.



**Commissioning** Our specialists carry out the installation step-bystep in your production hall and test your system for faultless functionality.



#### Training

We train your employees and service technicians in programming, operation and maintenance in our modern training centre

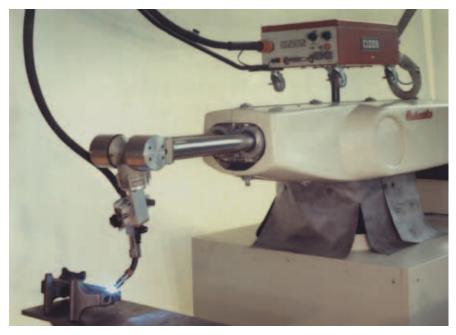


#### Service

Our competence team advices you on any extensions, modifications and retrofits of your existing robot and welding systems.

# ... to your success.

# **Pioneer work**



Delivery of the first welding robot: 1977

# For nearly 100 years we have been belonging to the pioneers concerning new manual and automated welding technologies.

We have already used industrial robots for automated MIG/ MAG welding since 1977. And shortly after that time we turned out to be a provider for complete solutions. Because everything comes from a single source – from the welding technology, robot mechanics and controller to positioners, software and sensors – we supply you all relevant components from a single source. For some years, many automation solutions have tended to apply systems with automated workpiece identification and loading and unloading processes. Also in welding technology, digitalisation and networking become more and more important. Our products are ready for the fourth industrial revolution. Already today tool carriers, robots, power sources and master controllers successfully communicate with each other in CLOOS welding systems all over the world.

With our solutions for automated welding we make you faster, more economic and more flexible - and thus fit for future production!



1982: Development and production of robot and controller from a single source: CLOOS

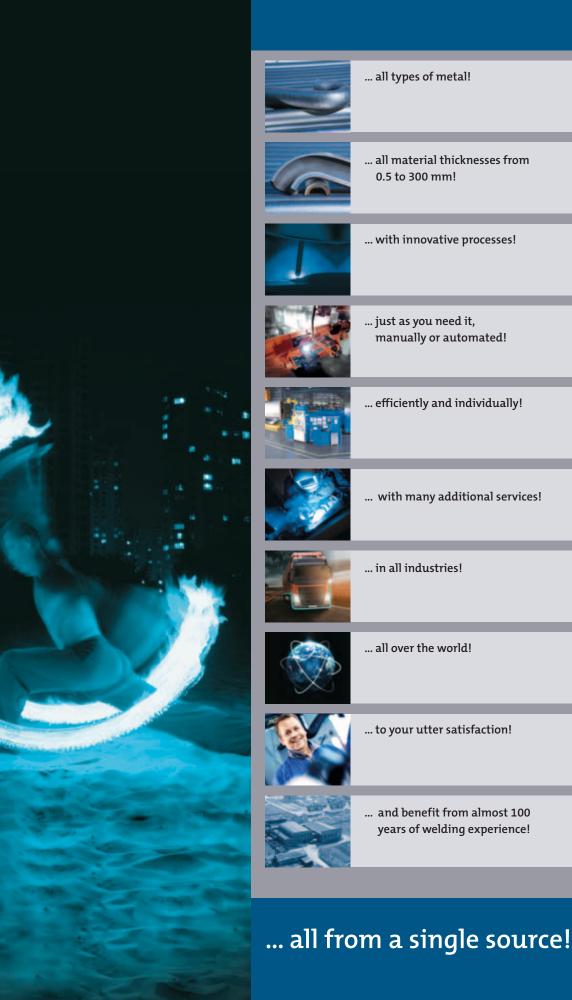


Delivery of chained systems: 1985

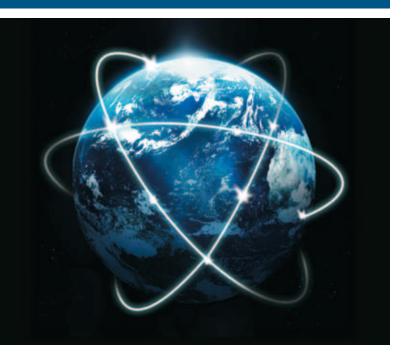


Robot assembly in 1995

# With CLOOS you weld and cut ...



# All over the world!



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